

Problem 7:

$$a) Z(T) = \frac{1}{C_N} \int d\vec{x}^N e^{-\beta H(\vec{x}^N)} = \frac{V^N}{h^{3N} N!} \int d^3\vec{p}_1 \dots d^3\vec{p}_N e^{-c\beta \sum_{i=1}^N |\vec{p}_i|}$$

$$= \frac{V^N}{h^{3N} N!} \left(\int d^3\vec{p} e^{-c\beta |\vec{p}|} \right)^N \quad (2)$$

$$\stackrel{\substack{\uparrow \\ \text{polar coordinates}}}{=} \frac{V^N}{h^{3N} N!} \left(4\pi \int_0^\infty dp p^2 e^{-c\beta p} \right)^N = \frac{V^N}{h^{3N} N!} \left(\frac{4\pi h_0^3 T^3}{c^3} \int_0^\infty dp p^2 e^{-T p} \right)^N$$

$$= \frac{1}{N!} \left(\frac{V 8\pi h_0^3 T^3}{c^3 h^3} \right)^N \quad (2)$$

$$b) F = -k_B T \ln Z(T) = -N k_B T \ln \left[8\pi V \left(\frac{k_B T}{hc} \right)^3 \right] + k_B T \ln N! \quad \stackrel{\approx N \ln N - N}{\approx}$$

$$= -N k_B T \left\{ 1 + \ln \left[8\pi \frac{V}{N} \left(\frac{k_B T}{hc} \right)^3 \right] \right\} \quad (2)$$

$$c) P = - \left(\frac{\partial F}{\partial V} \right)_{N,T} = -(-N k_B T) \left(\frac{\partial \ln V}{\partial V} \right)_{N,T} = \frac{N k_B T}{V}$$

$$\Rightarrow PV = N k_B T \quad (1)$$

$$d) U = \left(\frac{\partial}{\partial \beta} \ln Z(T) \right)_{N,V} = - \left(\frac{\partial}{\partial \beta} N \ln \beta^{-3} \right)_{N,V} = \frac{3N}{\beta} = 3N k_B T \quad (1)$$

Problem 8.

$$a) Z(T) = \sum_{\{n_i\}} e^{-\beta(E_0 - Lf)} = \sum_{n_i \in \{0,1\}} \dots \sum_{n_N \in \{0,1\}} e^{-\beta \sum_{i=1}^N \epsilon_{n_i} + \beta f \sum_{i=1}^N n_i}$$

$$\stackrel{\textcircled{2}}{=} \left(\sum_{n_i \in \{0,1\}} e^{-\beta \epsilon_{n_i} + \beta f l_{n_i}} \right)^N = \left(e^{-\beta \epsilon_a + \beta f l_a} + e^{-\beta \epsilon_b + \beta f l_b} \right)^N \quad \textcircled{1}$$

$$b) U = - \left(\frac{\partial \ln Z(T)}{\partial \beta} \right) = + N \frac{(\epsilon_a - f l_a) e^{-\beta \epsilon_a + \beta f l_a} + (\epsilon_b - f l_b) e^{-\beta \epsilon_b + \beta f l_b}}{e^{-\beta \epsilon_a + \beta f l_a} + e^{-\beta \epsilon_b + \beta f l_b}} \quad \textcircled{2}$$

$$c) \langle L \rangle = \left\langle \sum_{i=1}^N l_{n_i} \right\rangle = \frac{1}{\beta} \left(\frac{\partial \ln Z(T)}{\partial f} \right)_{\beta, N} \quad \textcircled{2}$$

$$= N \frac{l_a e^{-\beta \epsilon_a + \beta f l_a} + l_b e^{-\beta \epsilon_b + \beta f l_b}}{e^{-\beta \epsilon_a + \beta f l_a} + e^{-\beta \epsilon_b + \beta f l_b}} \quad \textcircled{2}$$

at $\epsilon_a = \epsilon_b$ and $f = 0$:

$$\langle L \rangle = N \frac{l_a e^{-\beta \epsilon_a} + l_b e^{-\beta \epsilon_a}}{e^{-\beta \epsilon_a} + e^{-\beta \epsilon_a}} = N \frac{l_a + l_b}{2} \quad \textcircled{1}$$

If (roughly) half of the building blocks are in state a and half of the building blocks are in state b the entropy is maximized. In the absence of energetic reasons ($\epsilon_a = \epsilon_b$, $f = 0$) this is therefore the preferred state. $\textcircled{2}$

Problem 9:

$$P_{P_2}(r) = \int d\vec{x}^N g(\vec{x}^N) \delta(|\vec{r}_1 - \vec{r}_2| - r) \quad (1)$$

$$= \frac{V^N \int d\vec{r}_1 \dots \int d\vec{r}_N e^{-\sum_{i=1}^N \frac{\beta}{2m} \vec{r}_i^2} \delta(|\vec{r}_1 - \vec{r}_2| - r)}{V^N \int d\vec{r}_1 \dots \int d\vec{r}_N e^{-\sum_{i=1}^N \frac{\beta}{2m} \vec{r}_i^2}}$$

$$= \frac{\int d\vec{r}_1 \int d\vec{r}_2 e^{-\frac{\beta}{2m} \vec{r}_1^2 - \frac{\beta}{2m} \vec{r}_2^2} \delta(|\vec{r}_1 - \vec{r}_2| - r)}{(\int d\vec{r} e^{-\frac{\beta}{2m} r^2})^2} \quad (2)$$

$$= \frac{\int d\vec{p} \int d\vec{r} e^{-\frac{\beta}{m} \vec{p}^2} e^{-\frac{\beta}{4m} \vec{r}^2} \delta(|\vec{r}| - r)}{V^2 \lambda_{0T}^{6/2}} \quad (3)$$

$$= \frac{\sqrt{m \pi \lambda_{0T}}^3}{(2 \pi m \lambda_{0T})^3} \int d\vec{r} e^{-\frac{\beta}{4m} \vec{r}^2} \delta(|\vec{r}| - r)$$

$$= \frac{1}{8(m \pi \lambda_{0T})^{3/2}} 4\pi e^{-\frac{\beta}{4m} r^2} r^2 = \frac{1}{2\sqrt{\pi}} \frac{1}{(m \lambda_{0T})^{3/2}} r^2 e^{-\frac{\beta}{4m} r^2} \quad (2)$$